# **Product Guide**



# EBDSPIR-AT-PRM-LV

# RF ceiling PIR presence detector – Switching 12-24V AC/DC

## Overview



The EBDSPIR-AT-PRM-LV is a passive infrared (PIR) motion sensor provides automatic control of low voltage loads including lighting and BMS systems.

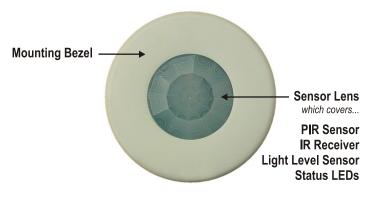
Functioning as a presence detector, the unit can turn lights on when a room is occupied and off when the room is empty. Optional settings allow lights to be turned off in response to ambient daylight. The unit also includes stored scenes for versatile manual on / off control of lighting.

The EBDSPIR-AT-PRM-LV can be used as a standalone unit or integrated with other devices as part of a system. The built-in RF transceiver allows wireless communication with all other **An-10**<sup>®</sup> compatible products, e.g. the AT-BB-IN Input Unit, useful for push-button scene selection and absence detection.

All functionality is fully programmable.

## **Features**

#### Front features



#### **PIR Sensor**

Detects movement within the unit's detection range, allowing load control in response to changes in occupancy.

### **IR Receiver**

Receives control and programming commands from an IR (infrared) handset.

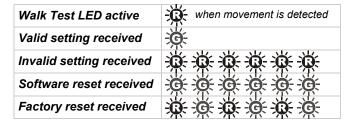
### **Light Level Sensor**

Monitors the ambient light level, allowing load control based on minimum and maximum Lux Level.

### **Status LEDs**

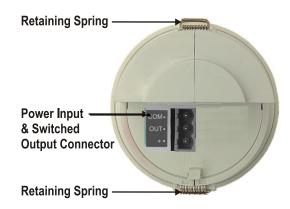
These flash Red and/or Green to indicate the following:

Power Input & Switched Output Connector (Channel 1)



Used to connect mains power to the unit and to connect a switched load.

#### Back features



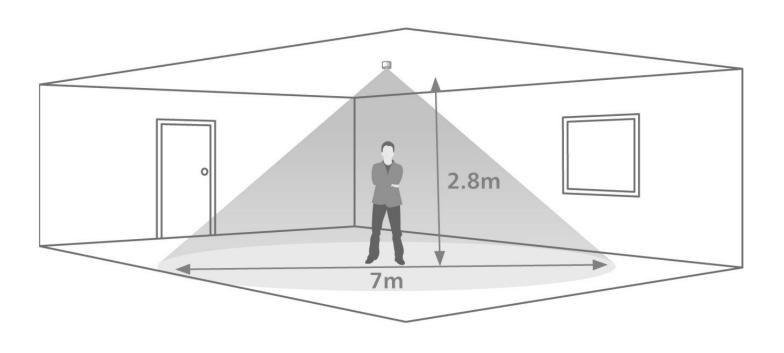
# Installation

### **Choosing a Suitable Location**

The EBDSPIR-AT-PRM-LV is designed to be ceiling mounted and must satisfy the following criteria:

- Avoid positioning the unit where direct sunlight may enter the sensor element.
- Do not site the sensor within 1m of any lighting, forced air heating or ventilation.
- Do not fix the sensor to an unstable or vibrating surface.
- Position the sensor so that the occupants of the room fall inside the detection zone shown in below.
   Note that the detection zone illustrated is based on a recommended mounting height of 2.8m. A lower height will decrease the overall size of the detection zone.

# **Detection pattern**



Area of high sensitivity

Area of lower sensitivity

Detection pattern

### **Mounting Methods**

The EBDSPIR-AT-PRM-LV is designed to be mounted using either:

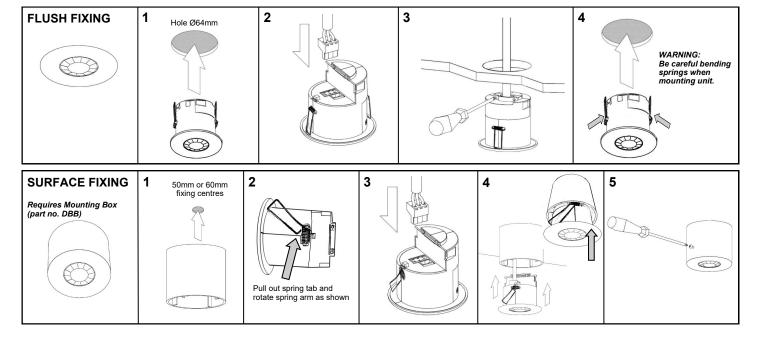
- Flush fixing, or
- Surface fixing, using the optional Surface Mounting Box (part no. DBB).

Both methods are illustrated in below.

### **IMPORTANT NOTICE!**

This device should be installed by a qualified electrician in accordance with the latest edition of the IEE Wiring Regulations and any applicable Building Regulations.

### Mounting procedures

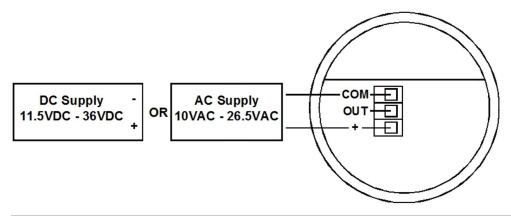


### **Choosing a Suitable Location**

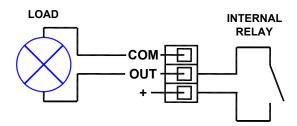
The detector should be sited so that the occupants of the room fall inside the detection pattern shown opposite).

- Avoid positioning the unit where direct sunlight may enter the sensor element.
- Do not site the sensor within 1m of any lighting, forced air heating or ventilation.
- Do not fix the sensor to an unstable or vibrating surface.
- Avoid metallic objects directly in front of the sensor head.

### Input connections



### **Load connections**



# Power-up test procedure

When power is applied to the unit, the load will turn on immediately.

Vacate the room or remain very still and wait for the load to switch off (this should take around 10 minutes).

Check that the load switches on when movement is detected.

The unit is now ready for programming.

# Fault finding

#### What if the load does not turn ON?

- Check that the live supply to the circuit is good.
- Check that the load is functioning by bypassing the sensor (e.g. link terminals L and L/ Out on Channel1).
- Check that the unit is correctly addressed, see 'Step 1: Set channel addresses and channel load type' on page 7.
- If the detection range is smaller than expected, check the diagrams in page 2. Rotating the sensor slightly may
  improve the detection range.

HINT: The Walk Test LED function can be used to check that the unit is detecting movement in the required area (see page 8 for further details).

#### What if the load does not turn OFF?

- Ensure that the area is left unoccupied for longer than the Time Adjustment Period (default is 10 minutes).
- Ensure that the sensor is not adjacent to circulating air, heaters or lamps.

HINT: The Walk Test LED function can be used to check that the unit is detecting movement in the required area (see page 8 for further details).

# **Basic programming**

The functionality of the EBDSPIR-AT-PRM-LV Sensor is controlled by a number of parameters which can be changed or programmed by any of the following devices:

- **UHS4** Infrared Handset
- UNLCDHS Infrared Handset (with LCD)

is recommended and the following procedures are based on using this device.

Point the handset at the Sensor and send the required programming commands to the unit as shown in Steps 1, 2 and 3.

Valid commands will be indicated by a green LED flash. See page 1 for details of other LED responses.

For most basic programming operations the UHS4 handset

## Step 1: Set channel addresses and channel load type

The Sensor has one output channel:

• Channel 1 - Switched Output

and one input channel:

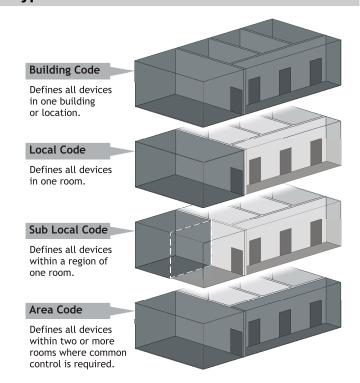
Channel 3 - PIR Sensor

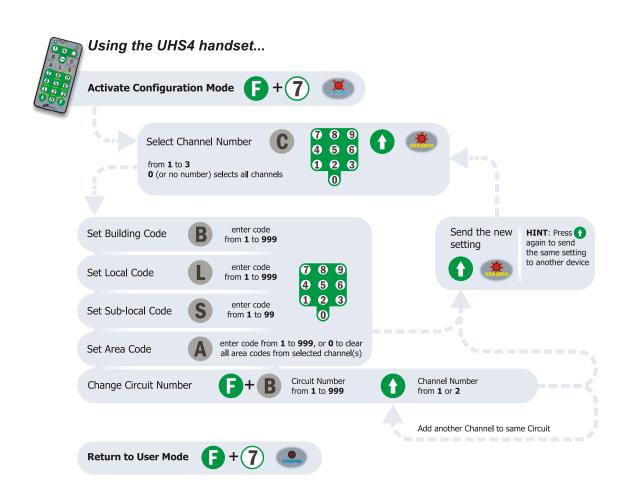
To relate the function of different channels it is necessary to set the addresses correctly. For example, a scene select message sent from a device with a Local Code of 1 will only be actioned by devices that also have a Local Code of 1.

To program the settings for a specific channel on the Sensor you must specify the appropriate channel number (i.e.1 to 3) using the programming device.

If no channel number (or channel 0) is specified, all channels will be set to the same address.

The output channel also has a Circuit number. This allows different physical channels to be linked and controlled as a single Circuit.





# Basic programming

### Step 2: Set-up sensor functionality

#### **Detection Mode**

The Detection Mode for the output Channel 1 can be set to behave in Presence or Absence mode:

- Presence mode allows a channel to turn on when movement is detected. Once turned on, if no movement is detected the Time Adjustment (10 minutes by default) the channel will turn off.
- Absence mode requires the channel to be turned on by some other means (e.g. by issuing a Scene Select message via an Input Unit or IR Handset). Once turned on, if no movement is detected for period of time (the Time Adjustment) the channel will turn off.

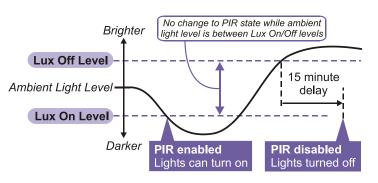
In either case, sensitivity to movement of the PIR sensor (Channel 3) can be adjusted using the Sensitivity parameter (set to 5 by default).

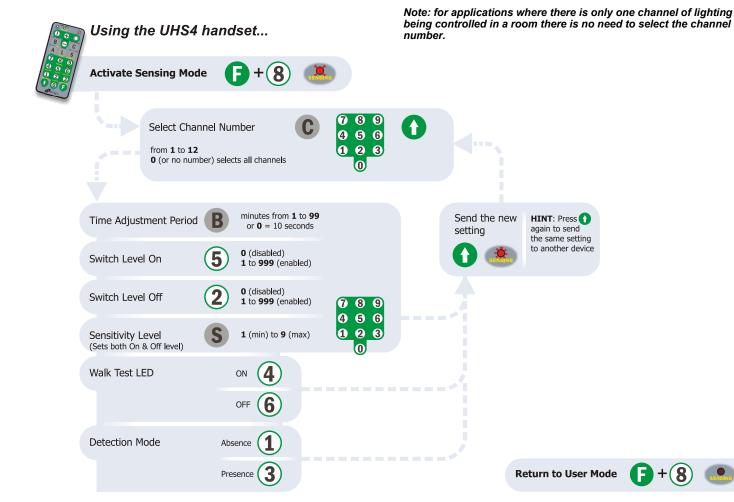
HINT: To assist in setting the Sensitivity, turn on the Walk Test LED which will flash red when movement is detected.

By default when the detector turns on Local Scene 1 is selected. When the detector turns off Local Scene 20 is selected. See 'Scenes Used for Occupancy Detection' in Step 3 for further details.

#### Switch Level On/Off

Occupancy detection can be made dependant on the ambient light level using the Lux On Level and Lux Off Level parameters.





### Step 3: Re-program scenes

The EBDSPIR-AT-PRM-LV has capacity to store 20 Local Scenes and 120 Area Scenes. By default all Scenes are pre-programmed with the following channel levels, but these can be changed as required:

	Loca	l Scer	nes					
	1	2	3	4	5	6	 19	20
Ch1	on	on	on	on	on	on	 on	off
	Area	Scen	es					
	101	102	103	104	105	106	 119	220
Ch1	on	on	on	on	on	on	 on	off

NOTE: Local Scene 20 and Area Scene 120 are designated 'off' scenes within a system and should normally be programmed with all channels off or at zero.

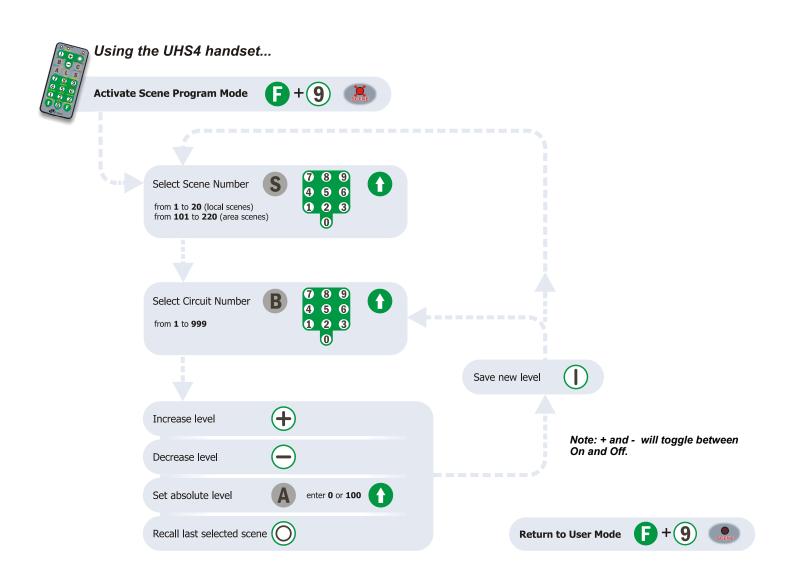
Scenes can be recalled by using an IR Handset or by a switch/button plate via an AT-BB-IN Input Unit.

### **Scenes Used for Occupancy Detection**

If movement is detected (in Presence mode), Local On Scene 1 is selected. By default this switches Channel 1 On.

If no movement is detected for the Time Adjustment Period (in Presence or Absence mode), Local Off Scene 20 is selected. By default this switches Channel 1 Off.

NOTE: These 'On' and 'Off' Scene selections cannot be changed using the UHS4 handset. You can, however, reprogram, on or off values, for Scenes 1 and 20 if required.



# **Advanced programming**

The tables on pages 12 to 14 give a summary of all programmable parameters for the EBDSPIR-AT-PRM-LV Sensor.

Parameter Name	Default Value	Range / Options	Description	Programming Devices	
					UNLCDHS
For Device					
Product ID	Automatically assigned by the device	1 to 999	A number used to uniquely identify each device within a range of devices that are set to the same Local Code.		✓
Building Code	1	1 to 999	A number shared by all devices that belong to the same building or system.	<b>✓</b> ✓	
Lock	0	Enable (1) or disable (0)	Lock the An-10 network. Prevents more devices joining the network.	x 🗸	
For Channel 1 (Sw	itched Output)				
Local Code	1	1 to 999	A number corresponding to the Local Code of all devices to be controlled by an associated input channel.	✓	✓
Sub Local Code(s)	Not set	1 to 99 0 to clear	A number corresponding to the Sub Local Code of all devices to be controlled by an associated input channel. Up to 20 Sub Local Codes can be set for the switched output Channel 1.		✓
Area Code(s)	999	1 to 999 0 to clear	A number corresponding to the Area Code of all devices to be controlled by an associated input channel. Up to 32 Area Codes car be set for the switched output Channel 1.		<b>√</b>
Circuit Number	1	1 to 999	Sets the circuit number for this channel.	<b>✓</b> ✓	
Detection Mode	Presence	Presence or Absence	Presence mode allows the output to turn on when movement is detected and off when movement ceases. Absence mode allows the output to turn off when movement ceases, but must be manually turned on first.		✓
Output State	Set by Scene	0-100% 0=off	The current output state of the channel, for example as set by a Scene Select command.	✓	✓
Raise from off	1	Enable (1) or disable (0)	Enables raise from off feature.		✓
Lower from off	1	Enable (1) or disable (0)	Enables lower from off feature.	<b>x</b> 🗸	
Lux off period	0	0 to 999 in minutes (0=15 seconds)	Number of minutes above the Lux Off level before a lux switching decision is made.	g <b>x</b> 🗸	
Lux switching enabled	1	Enable (1) or disable (0)	Enables or disables the output channel to respond to lux switching commands.	x 🗸	
Detector enabled	1	Enable (1) or disable (0)	Enables the output channel to be controlled by detector occupancy.	x 🗸	
Detector inhibit period	0	0 to 255	Detector inhibit period in 100s of milliseconds (255 = 25 seconds).	×	✓

# Advanced programming

Parameter Name	Default Value	Range / Options	Description		Programming Devices	
					UNLCDHS	
For <b>Channel 3</b> (PIF	R Sensor)					
Local Code	1	1 to 999	A number corresponding to the Local Code of all devices to be controlled by this PIR input channel.	<b>✓ ✓</b>		
Sub Local Code	Not set	1 to 99	A number corresponding to the Sub Local Code of all devices to be controlled by this PIR input channel.	<b>✓</b> ✓		
Area Code(s)	Not set	1 to 999 0 to clear	A number corresponding to the Area Code of all devices to be controlled by this PIR input channel. Up to 10 Area Codes can be set for Channel 3.	<b>✓ ✓</b>		
Sensitivity On	5	1 (min) to 9 (max)	Sensitivity level for detecting movement when the detector is already on. *UHS4 sets Sensitivity On and Off to the same value.	<b>√</b> *		
Sensitivity Off	5	1 (min) to 9 (max)	Sensitivity level for detecting movement when the detector is off. *UHS4 sets Sensitivity On and Off to the same value.		<b>√</b>	
Walk Test LED	Off	On or Off	When set to On this causes a red LED to flash on the sensor when it detects movement. Use this feature to check for adequate Sensitivity On/Off levels.			
Lux on level (Switch level on)	400	0 (disabled) or 1 to 999	Sets a minimum light level below which the PIR sensor is enabled, allowing lights to be turned on by movement.	<b>✓</b> ✓		
Lux off level (Switch level off)	700	0 (disabled) or 1 to 999	Sets a maximum light level above which the PIR sensor is disabled, preventing lights from being turned on by movement.	<b>✓</b> ✓		
Power Up State	On	On or Off	When power is applied to the unit the PIR sensor goes through a settling down period of up to 40 seconds. With Power Up set to On, the outputs go to the last levels for up to 15 seconds, then the Local On Scene (scene 1 by default) is invoked plus the Time Adjustment Period, after which the Local Step/Off Scene (scene 20 by default) is invoked (assuming no movement is detected). With Power Up set to Off, the outputs go to the last levels until movement is detected.	g <b>x</b> 🗸		
Disable Detector	N	Y or N	Disables detection, leaving the relay output permanently off with the dimming output operational. This mode is used when the unit is for maintained illuminance only.	x 🗸		

# Advanced programming

Parameter Name	Default Value	Range / Options	Description		mming es	
				UHS4	UNLCDHS	
When movement is	When movement is detected					
Local On Scene	1	1 to 20	The local scene request sent to all devices with the Local Code specified.	×	✓	
Area On Scene	101	101 to 220	The area scene request sent to all devices with the Area Code(s) specified above, when movement is detected.  NOTE: The Area On Scene is ignored unless one or more Area Codes are set for the corresponding input channel and they match the Area Codes set in any output channel.	×	✓	
Time adjustment	10 mins	0 (10 seconds) 1 to 99 minutes	Once the detector is turned on, this value sets how long the lights will stay on once movement has ceased. The 10 second setting is for commissioning only.	✓	✓	
When no movemen	nt is detected for T	ime Adjustment				
Local Off Scene	20	1 to 20		×	✓	
Area Off Scene	220	1 to 20		×	✓	

# **Technical data**

Dimensions See diagrams opposite

Weight 0.1kg

Supply Voltage Min 11.5VDC max 36VDC, min

10VAC max 26.5VAC

Maximum Load Low voltage supply with relay

output rating 16A resistive 10A

inductive

Power consumption On 838mW, Off 505mW

Terminal Capacity 2.5mm<sup>2</sup>

Order code	Region	Radio frequency	Compliance
blank	European Union	868MHz	RED-2014/53/EU LVD-2014/35/EU
-A2	Australia & New Zealand	915MHz	AS/NZS 4268:2008

For further compliance information visit www.cpelectronics.co.uk/compliance



Receiver Class 2

Transmitter Duty Cycle <10% on g3 band (default band)

<0.1% on g2 band <1% on g1 band

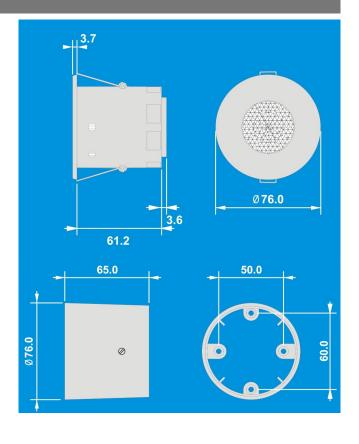
Range The maximum RF range between An-10

devices is 100m in free air and up to 30m indoors. However the materials used within a building will vary and this will impact upon the RF range. In reality the nature of how the An-10's hybrid-mesh works means that in most scenarios the individual range of an An-10 product will not be important.

Temperature 0°C to 35°C

Humidity 5 to 95% non-condensing

Material (casing) Flame retardant ABS Type Class 2



## Part numbers

AT-BB-IN RF Input unit AT-SL-R RF relay controller

AT-SL-R-SA RF relay controller (standalone)
AT-SL-DDR RF DALI/DSI + relay controller

AT-SL-DDR-SA RF DALI/DSI + relay controller (standalone)

AT-SL-ADR RF 1-10V + relay controller

AT-SL-ADR-SA RF 1-10V + relay controller (standalone)

VITM4-ATMOD RF Switching module
VITM6-ATMOD-AD RF VITM6 1-10V module
VITM6-ATMOD-DD RF VITM6 DALI/DSI module
UHS4 Programming IR handset
UNLCDHS Universal LCD IR handset







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